

ARM Cortex[®]-M 32-bit Microcontroller

NuMicro™ Family NuTiny-SDK-NUC505 User Manual

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1 OVERVIEW

NuTiny-SDK-NUC505 is the specific development tool for NuMicro NUC505 series. Users can use NuTiny-SDK-NUC505 to develop and verify the application program easily.

NuTiny-SDK-NUC505 includes two portions. One is NuTiny-EVB-NUC505 and the other is NuLink-Me. NuTiny-EVB-NUC505 is the evaluation board and Nu-Link-Me is its Debug Adaptor. Thus, users do not need other additional ICE or debug equipment.

The NuMicro™ NUC505 series 32-bit microcontrollers are embedded with ARM® Cortex®-M4F core for consumer and industrial applications which need high computing power and rich communication interfaces.

The ARM[®] Cortex[®]-M4F core within NuMicro™ NUC505 series can run up to 100 MHz and support DSP extensions and Floating Point Unit (FPU) function. The NuMicro™ NUC505 series supports 128 Kbytes embedded SRAM with zero-wait state and 2 Mbytes embedded SPI Flash memory, and is equipped with plenty of high performance peripheral devices, such as 24-bit Audio CODEC, USB2.0 High-speed Device, USB2.0 Full-speed Host, and other peripheral.



2 NUTINY-SDK-NUC505 INTRODUCTION

NuTiny-SDK-NUC505 uses the NUC505Y013Y as the target microcontroller. Figure 2-1 is NuTiny-SDK-NUC505 for NUC505 series, the left portion is called NuTiny-EVB-NUC505 and the right portion is Debug Adaptor called Nu-Link-Me.

NuTiny-EVB-NUC505 is similar to other development boards. Users can use it to develop and verify applications to emulate the real behavior. The on board chip covers NUC505 series features. The NuTiny-EVB-NUC505 can be a real system controller to design users' target systems, supports usb high speed interface, audio headphone out, audio line in and sdcad slot.

Nu-Link-Me is a Debug Adaptor. The Nu-Link-Me Debug Adaptor connects your PC's USB port to your target system (via Serial Wired Debug Port) and allows you to program and debug embedded programs on the target hardware. To use Nu-Link-Me Debug adaptor with IAR or Keil, please refer to "Nuvoton NuMicro™ IAR ICE driver user manual" or Nuvoton NuMicro™ Keil ICE driver user manual" in detail. These two documents will be stored in the local hard disk when the user installs each driver.

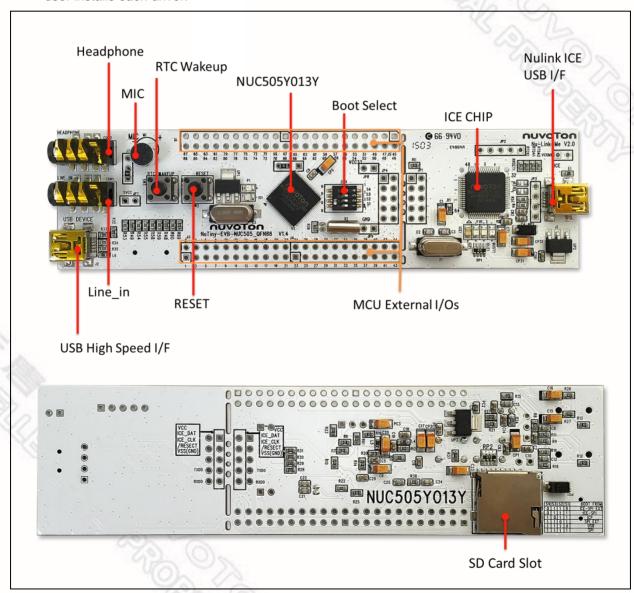


Figure 2-1 NuTiny-SDK-NUC505 (PCB Board)



2.1 NuTiny -SDK-NUC505 Jumper Description

NuTiny-SDK-NUC505 is the specific development tool for NuMicro NUC505 series. Users can use NuTiny-SDK-NUC505 to develop and verify the application program easily.

NuTiny-SDK-NUC505 includes two portions. One is NuTiny-EVB-NUC505 and the other is NuLink-Me. NuTiny-EVB-NUC505 is the evaluation board and Nu-Link-Me is its Debug Adaptor. Thus, users do not need other additional ICE or debug equipment.

2.1.1 Power Setting

• J1: USB port in Nu-Link-Me

• J2: USB port in NuTiny-EVB-NUC505

JP8: VCC33 Voltage connecter in NuTiny-EVB-NUC505

JP7: P5VCC Voltage connecter in NuTiny-EVB-NUC505

| POWER model | J1 USB port | J2 USB port | JP7 P5VCC | JP8 VCC33 |
|----------------|----------------------|----------------------|-------------------|---------------------|
| Model 1 | Connect to PC USB | х | х | Q X |
| Model 2 | X | Connect to PC USB | х | x |
| Model 3 | х | х | External 5V power | х |
| Model 3 | х | х | Х | External 3.3V power |

X: Unused.

Boot Select

| | S4 | S3 | S2 | S1 | BootFrom | Descriptions |
|---|----|----|-----|----|-------------|-------------------------------------|
| | 0 | 1 | 1 | 0 | ICE SPI EXT | ICE Mode with External SPI Flash |
| | 0 | 1 | 1 | 1 | ICE-SPI | ICE Mode with Internal SPI Flash |
| 2 | 1 | 0 | 1 | 1 | ICP | Boot from ICP Mode |
| | | 1 | 0 | 1 | SPI EXT | Boot from External SPI Flash |
| | 1 | | 1 | 0 | USB | Boot from USB |
| | 1 | | a 1 | 1 | SPI | Boot from Internal SPI Flash |



2.1.2 Debug Connector

- JP4: Connector in target board (NuTiny-EVB-NUC505) for connecting with Nuvoton ICE adaptor (Nu-Link-Me)
- JP1: Connector in ICE adaptor (Nu-Link-Me) for connecting with a target board (for example NuTiny-EVB-NUC505)

2.1.3 ICE USB Connector

J2: Mini USB Connector in Nu-Link-Me connected to a PC USB port

2.1.4 USB Host Connector

• CON3: USB A type Connector in NUC505 USB host function connected to USB device

2.1.5 USB High Device Connector

J4: Mini USB Connector in NUC505 USB device high speed function connected to PC USB port
 (Note) using the USB high speed device need external stable power for JP7

2.1.6 Extended Connector

• JP3, JP4, JP5 and JP7: Show all chip pins in NuTiny-EVB-NUC505

2.1.7 Reset Button

SW2: Reset button in NuTiny-EVB-NUC505

2.1.8 RTC wakeup Button

• SW3: RTC wakeup button in NuTiny-EVB-NUC505

2.1.9 Headphone

CON2: NUC505 audio headphones connect.

2.1.10 Line

CON1: NUC505 audio line in connect.

2.1.11 Power Connector

- JP7: 5 VCC connector in NuTiny-EVB-NUC505
- JP8: 3.3 VCC connector in NuTiny-EVB-NUC505
- JP9: GND connector in NuTiny-EVB-NUC505



2.2 Pin Assignment for Extended Connector

NuTiny-EVB-NUC505 provides NUC505YO13Y on board and the extended connector for QFN-88 pin. Table 2-1 is the pin assignment for NUC505YO13Y

| Pin No | Pin Name | Pin No | Pin Name | Pin No | Pin Name | Pin No | Pin Name |
|--------|--------------|--------|------------|--------|-----------------|--------|-----------|
| 01 | RESETn | 23 | RTC_VDD33 | 45 | GPB5 | 67 | SAR_VDD33 |
| 02 | GPD0 | 24 | RTC_RPWR | 46 | GPB5 | 68 | SAR_VSS33 |
| 03 | GPD1 | 25 | RTC_RWAKEn | 47 | GPB6 | 69 | GPA0 |
| 04 | GPB13 | 26 | RTX_XIN | 48 | GPB7 | 70 | GPA1 |
| 05 | GPB14 | 27 | RTC_XOUT | 49 | UD_CDET | 71 | GPA2 |
| 06 | GPB15 | 28 | GPA8 | 50 | GPB8 | 72 | GPA3 |
| 07 | GPB15 | 29 | GPA9 | 51 | GPB9 | 73 | GPA4 |
| 08 | GPC1 | 30 | GPA10 | 52 | VDD33 | 74 | GPA5 |
| 09 | GPC2 | 31 | GPA11 | 53 | HP_VDD33 | 75 | GPA6 |
| 10 | VDD33 | 32 | GPA12 | 54 | LHP_OUT | 76 | GPA7 |
| 11 | GPC3 | 33 | GPA13 | 55 | VCMBF | 77 | VDD12 |
| 12 | GPC4 | 34 | GPA14 | 56 | RHP_OUT | 78 | GPB10 |
| 13 | GPC5 | 35 | GPA15 | 57 | HP_VSS33 | 79 | GPB11 |
| 14 | GPC6 | 36 | GPC7 | 58 | VMID | 80 | GPB12 |
| 15 | VDD12 | 37 | GPC8 | 59 | AVDD33 | 81 | VDD33 |
| 16 | XIN | 38 | GPC9 | 60 | MIC1P | 82 | GPC11 |
| 17 | XOUT | 39 | GPC10 | 61 | MIC1N | 83 | GPC12 |
| 18 | PLL_UD_VDD12 | 40 | VDD33 | 62 | LLINEIN/MICBIAS | 84 | GPC13 |
| 19 | UD_DM | 41 | GPB0 | 63 | VDD12 | 85 | GPC14 |
| 20 | UD_DP | 42 | GPB1 | 64 | GPD2 | 86 | AVDD |
| 21 | UD_VDD33 | 43 | GPB2 | 65 | GPD3 | 87 | VOUT |
| 22 | UD_REXT | 44 | GPB3 | 66 | GPD4 | 88 | AGND |

Table 2-1 Pin Assignment for NUC505YO13Y



2.3 NuTiny-SDK-NUC505 PCB Placemen

Users can refer to Figure 2-2 for the NuTiny-SDK-NUC505 PCB placements.

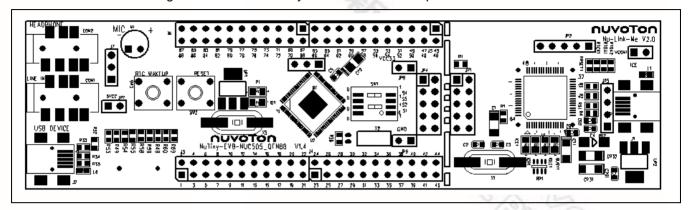


Figure 2-2 NuTiny-SDK-NUC505 PCB Placement



3 HOW TO START NUTINY -SDK-NUC505 ON THE KEIL MVISION® IDE

3.1 Keil uVision® IDE Software Download and Install

Please visit the Keil company website (http://www.keil.com) to download the Keil μ Vision IDE and install the RVMDK

3.2 Nuvoton Nu-Link Driver Download and Install

Please visit the Nuvoton company NuMicro $^{^{\intercal}}$ website (http://www.nuvoton.com/NuMicro $^{^{\intercal}}$ to download "NuMicro $^{^{\intercal}}$ Keil μ Vision IDE driver" file. When the Nu-Link driver has been well downloaded, please unzip the file and execute the "Nu-Link Keil Driver.exe" to install the driver.

3.3 Hardware Setup

The hardware setup is shown as Figure 3-1

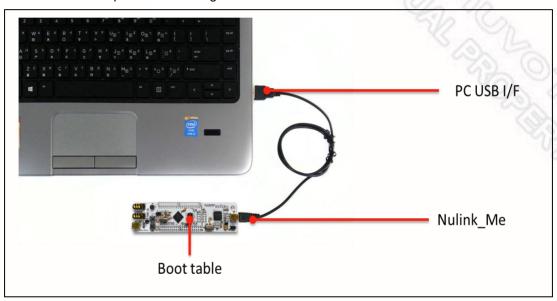


Figure 3-1 NuTiny-SDK-NUC505 Hardware Setup

Boot form ICE-SPI mode to select ICE Mode with Internal SPI Flash

| S4 | S3 | S2 | S1 | Boot From | Descriptions |
|-----|-------|----|----|-------------|-------------------------------------|
| 0 | 1 | 1 | 0 | ICE SPI EXT | ICE Mode with External SPI Flash |
| 0 | 1 | 1 | 1 | ICE-SPI | ICE Mode with Internal SPI Flash |
| 1 4 | 0 | 1 | 1 | ICP | Boot from ICP Mode |
| 1 | 10 TO | 0 | 1 | SPI EXT | Boot from External SPI Flash |
| 1 | 1 | | 0 | USB | Boot from USB |



| 1 1 | 1 | 1 | SPI | Boot from Internal SPI Flash |
|-----|---|---|-----|------------------------------|
|-----|---|---|-----|------------------------------|

3.4 Smpl_NuTiny-NUC505 Example Program

This example demonstrates the ease of downloading and debugging an application on a NuTiny-SDK-NUC505 board. It can be found on Figure 3-2 list directory and downloaded from Nuvoton NuMicro $^{\text{TM}}$ website.

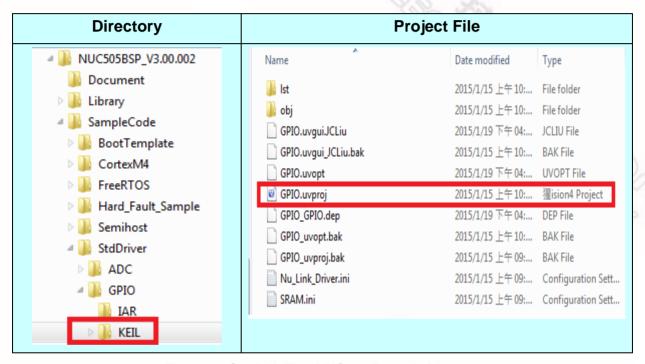


Figure 3-2 Smpl NuTiny NUC505 Example Directory

To use this example:

The LED will toggle on the NuTiny-EVB-NUC505 board.



■ Project-Open

Open the Smpl_NuTiny.uvproj project file

Project - Build
Compile and link the Smpl_NuTiny application

Start debug mode

Using the debugger commands, you may:

- Review variables in the watch window
- ◆ ^{{+}} Single step through code



■ Flash – Download

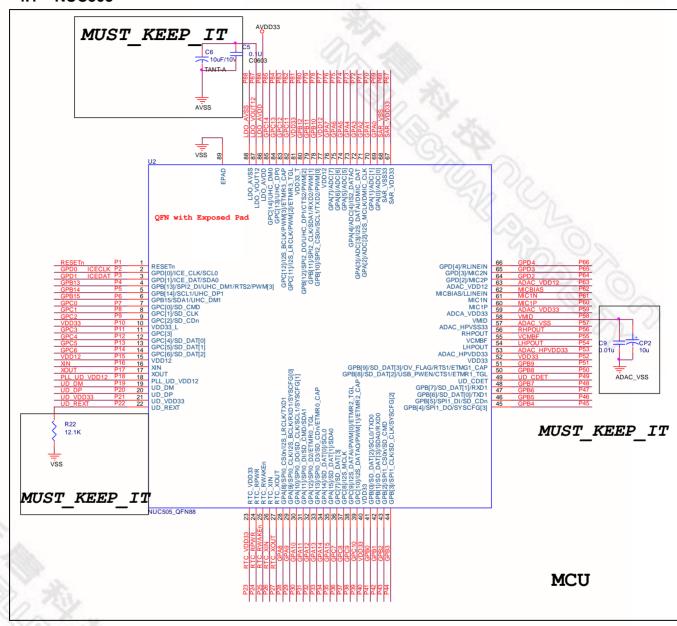
Program the application code into onchip Flash ROM

- Reset the device
- Run the application



4 NUTINY-EVB-NUC505 SCHEMATIC

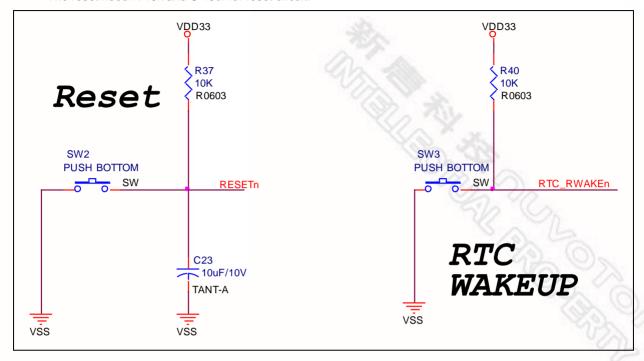
4.1 NUC505





4.2 RESET and RTC WAKEUP Button

The reset need R 10k and C 10uf for reset circuit.



4.3 Crystal

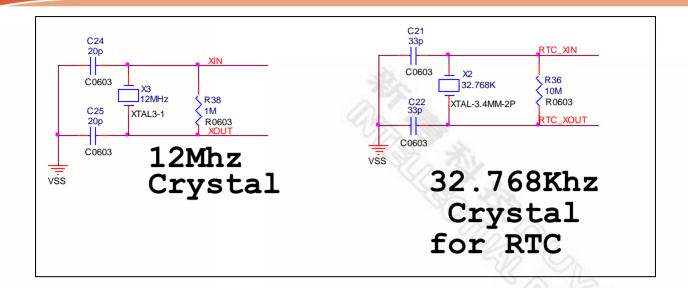
4.3.1 HXT:High Speed Crystal(12 Mhz)

For C24 and C25 is recommended to use high-quality ceramic capacitors in the 5pF~20pF range, designed for high-frequency applications and selected to meet the requirements of the crystal or resonator. C24 and C25 are usually the same value. The crystal manufacturer typically specifies a load capacitance that is the series combination of C24 and C25. The PCB and MCU pin capacitances must be included when sizing C24 and C25 (20pF can be used as a rough estimation of the combined pin and board capacitance), external resister need 1 MHz

4.3.2 LXT: Low Speed Crystal(32.768 Khz)

For C21 and C22 is recommended to use high-quality ceramic capacitors in the 5~33 pF range, designed for RTC applications and selected to meet the requirements of the crystal or resonator, external resister need 10Mhz

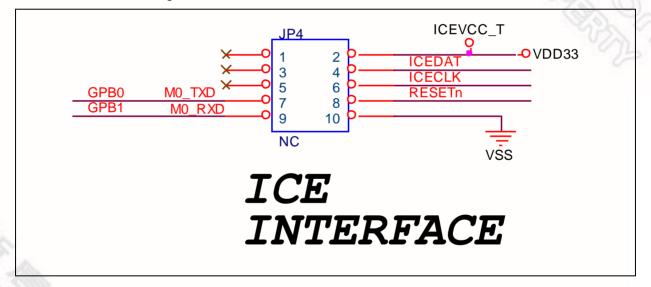
Applications requiring oscillators on NUC505 series MCUs must take PCB layout into consideration. The oscillators on NUC505 series MCUs consume very little current, and it sometimes makes the oscillator circuit sensitive to neighboring circuits. The following lists some PCB design guidelines:



4.4 ICE Interface

nuvoTon

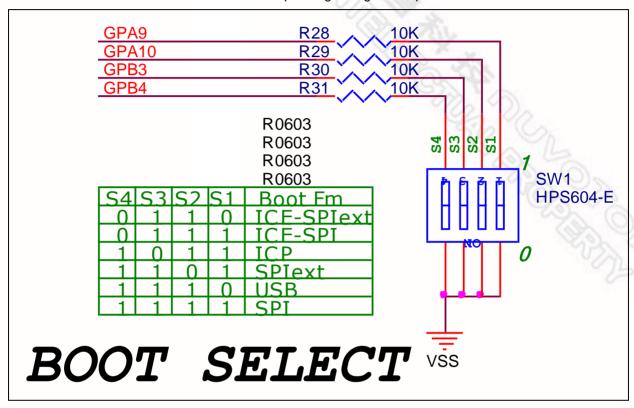
For ICE Mode debug or ICP Mode download code to flash





4.5 Boot Select

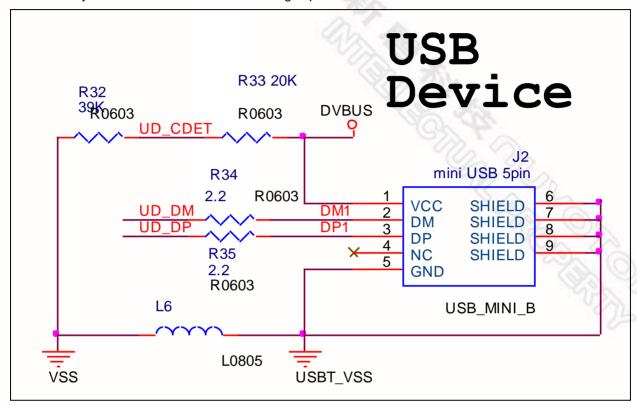
The power-on setting is used to configure the chip to enter the specified state when the chip is powered up or reset. Since each pin of power on setting has an internal pulled-up resistor when in reset period. If the application needs to set the configuration to "0", the proper pull-down resistor of 10KOhm must be added for the corresponding configuration pins.





4.6 USB 2.0 High Speed Device

The layout rule needs to take USB 2.0 high speed device.



4.6.1 PCB Layer Stack-up

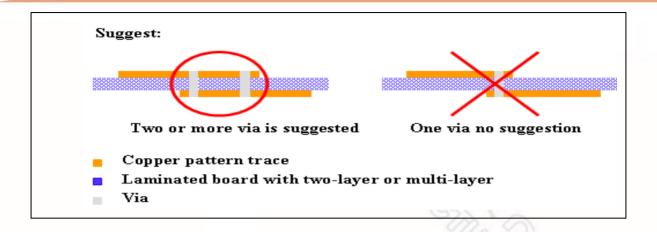
For a USB 2.0 high-speed design, recommend to use at least a four-layer PCB for best signal characteristics. The majority of signal traces should run on a single layer, next to this layer should be the GND plane, which is solid with no cuts. Avoid running signal traces across a split in the ground or power plane. Minimizing the number of signal vias reduces EMI by reducing inductance at high frequencies.

If you attempt a two-layer board, you will need to reduce the thickness of the PCB along with increasing separation of traces and increased trace widths to maintain the impedance match of the D+ and D- data lines. To put things in perspective, what would be D+ and D- lines at 6mil trace and 6mil space in a four layer board become 18mils wide with 8mil spacing in a two-layer board.

4.6.2 Through Hole for D+ and D-

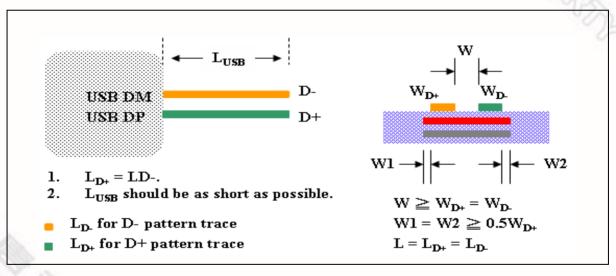
For the two-layer or multi-layer of PCB, when the signals of D+ and D- need to be through another layer, in which the resistively of through hole should be concerned. To lower the resistively issue for the sensitivity case, the two-via or multi-via should be adapted, as shown in the following figure.





4.6.3 Signal Trace for D+ and D-

To avoid the trace effect signal for the eye diagram, the trace length should be almost the same of D+ and D-. Then, the characteristic impedance should be a symmetrical path for the differential end of the USB port. The characteristic impedance should be 90 Ω for USB 2.0 high speed. For reducing the trace length, the USB terminal should be as close as the USB port of NUC505 series MCUs.



4.6.4 Others PCB design guideline for USB 2.0-

- Control differential impedance on USB traces (90 Ohms)
- Isolate USB traces from other circuitry and signals
- Keep bulk capacitors for down-stream port's VBUS power close to connectors
- Isolate crystal and oscillator
- Isolate VRES resistor and keep short traces
- Bypass capacitors placed on bottom side to reduce board space



4.7 Power

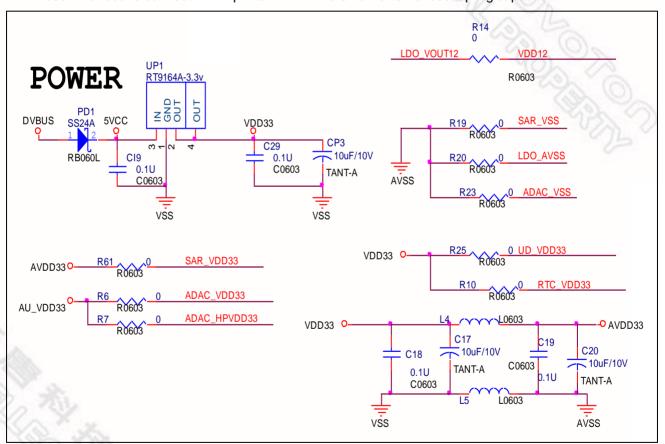
The ADAC_VDD33, ADAC_HPVDD33, RTC_VDD33 need stable power in user application, 0 ohm can direct short in user application.

- The VDD pins must be connected to 3.3V with external decoupling capacitors. (a 0.1uF capacitor for each VDD pin and a 1uF capacitor for the whole chip).
- The AVDD pin recommend be connected to two external decoupling capacitors (0.1uF+10nF).

To keep the analog power stable, additional precautions need to be taken to filter analog noise. The following are two suggestions for the board level designing:

• AVDD can be connected to VDD through a ferrite bead.

The RTC _VDD33 pin also powers the RTC unit, allowing the RTC to operate even when the main digital supply (VDD) is turned off. If no external battery is used in the application, it is highly recommended to connect VBAT pin to VDD with a 0.1uF external decoupling capacitor.



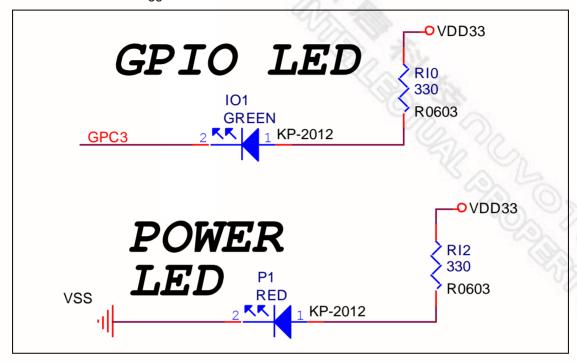
Note: The 0 ohm resister can short in user application.



4.8 **LED**

The P1 LED shows when VDD33 has provider.

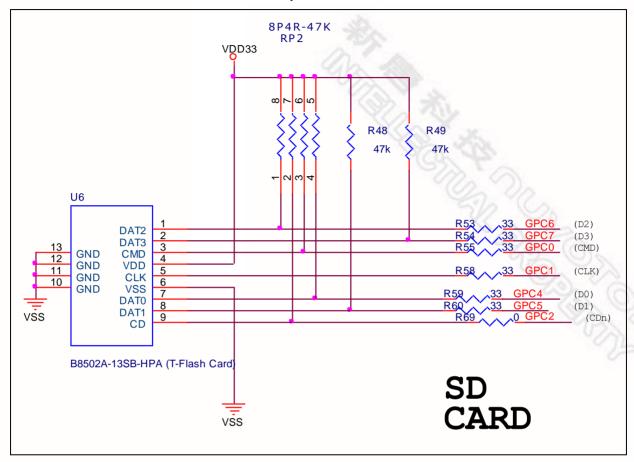
GPC3 can control IO1 to toggle LED





4.9 Micro SDCard Slot

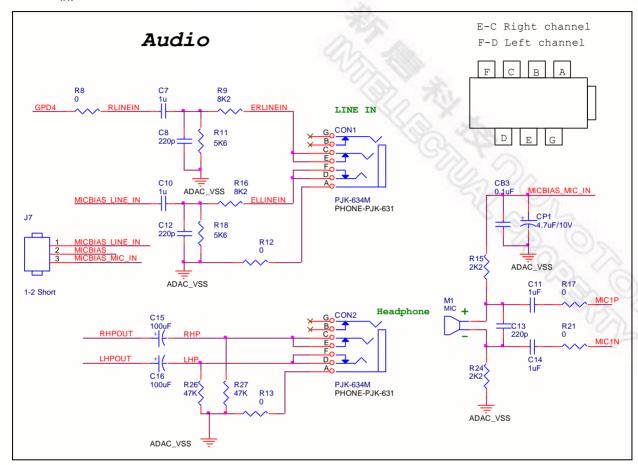
U6 is micro SD Card Slot, it is access by SHDC mode, Max clock can run 50 Mhz





4.10 Audio Line In, Headphone out and MIC

For audio application, the headphone out for audio out, J7 is bais voltage select for MIC or line in.



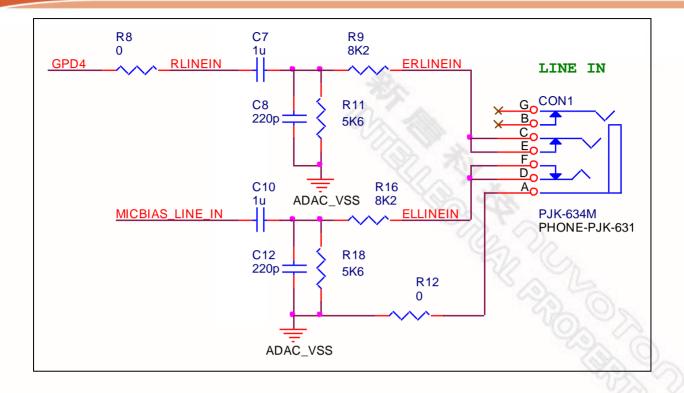
4.10.1 Audio Line In

The device provides left and right channel line-in inputs. The inputs are high impedance, low capacitance AC coupled.

All inputs include independent PGA (programmable gain amplifier) and mute function. Passive RF and active Anti-Alias filters are also incorporated within the line inputs to prevent high frequencies aliasing into the audio band or otherwise degrading performance.

The inputs are biased internally through the operational amplifier to Bais. The external components required to complete the line input application are shown in the following figure.

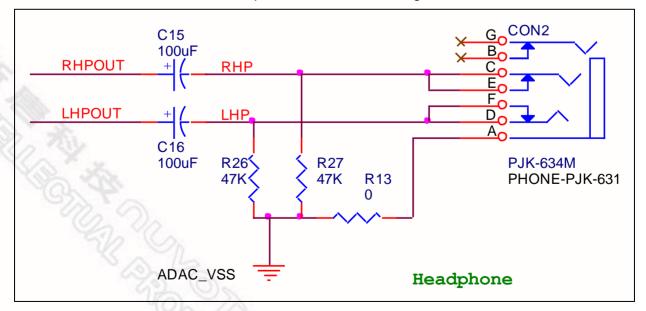




4.10.2 Audio Headphone out

This device provides two low impedance line outputs (LHPOUT and RHPOUT), suitable for driving typical line loads of impedance 10k and capacitance 50pF.

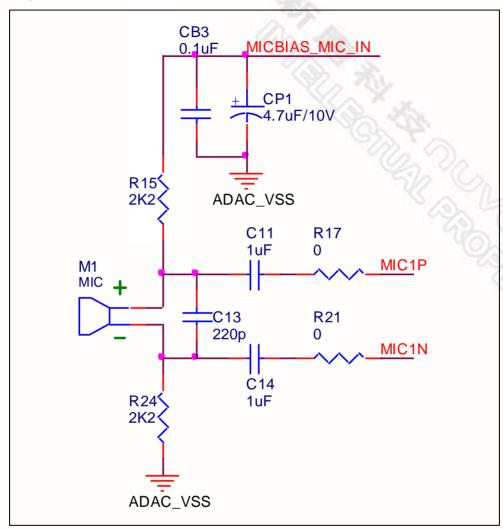
The recommended external components are shown in the figure below:





4.10.3 Audio Headphone out

The device supports 2 types of Microphone inputs that can be either differential or single-ended, The differential mode as shown below.





5 REVISION HISTORY

| Date | Revision | Description | |
|------------|----------|----------------------|--|
| 2015.02.08 | 1.00 | 1. Initially issued. | |



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